

# Deep Reinforcement Learning based Elasticity-compatible Heterogeneous Resource Management for Time-critical Computing

---

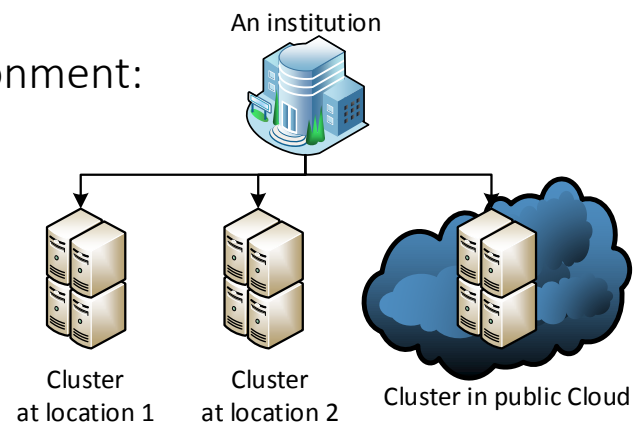
Zixia Liu, University of Central Florida  
Liqiang Wang, University of Central Florida  
Gang Quan, Florida International University



# Background

- Expanding needs for data analytics call for greater scale computing infrastructure, multi-cluster computing environment shows its benefits and necessity in this.
  - Example: institution-owned geo-distributed clusters, hybrid-cloud, etc.
- An efficient resource management is needed.
- Many features to consider for resource management, also including cluster heterogeneity and elasticity.
- To consider features in an integration, We presents a DRL based resource management in such environment.

An example of a multi-cluster environment:

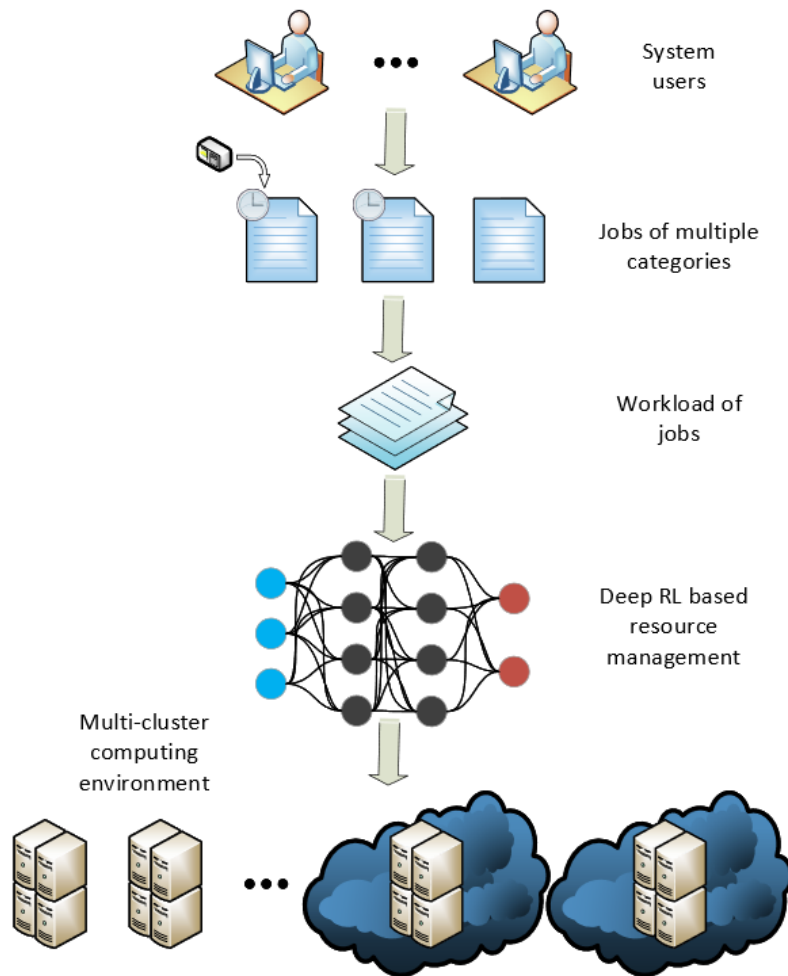


# Contribution

- We propose a DRL based approach utilizing:
  - LSTM model and
  - multi-target regression with partial model sharing mechanismand compare its effectiveness with baselines and another RL approach.
- The approach is designed for distributed multi-cluster computing environments considering:
  - its heterogeneity and
  - being elasticity-compatible.
- It provides scheduling support for time-critical computing in such a multi-cluster environment.



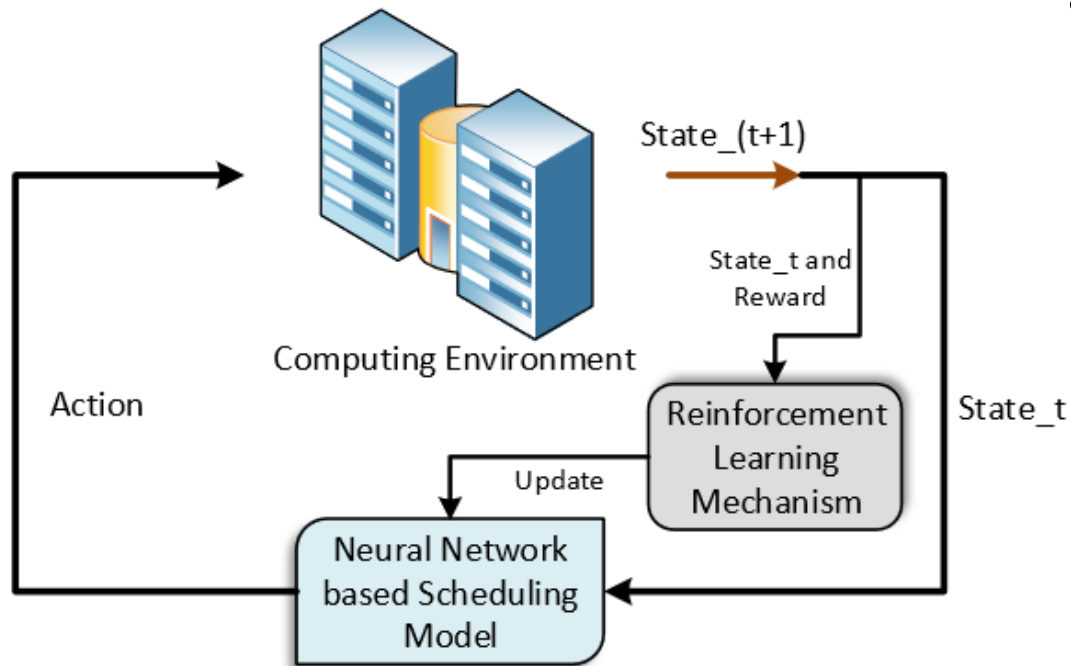
# Problem Description



- Cluster in environment expresses its computing resources as the number of executors it could provide.
- Executors of different clusters may have different computing capabilities.
- Some clusters may be elastic.
- Goals for resource management:
  - (1) Reducing occurrences of missing temporal deadline events.
  - (2) Maintaining a low average execution time ratio for a hybrid workload containing multiple time-critical and general jobs.

# DRL based Approach

- Brief introduction of Reinforcement learning



- We are using:
  - Reinforcement learning on deep neural networks
  - With neural networks serving as value estimators.



# DRL based Approach

- Challenges:
  - How to represent system status and job information as state for such environment?
  - How should we define value?
  - Effective value estimator?
- Environment
- Action set
- Episode
- State
  - Computing system features and status
  - Scheduling job information

**Table 1: State representation in our deep reinforcement learning model for 5 clusters**

<b>Vector Component</b>	<b>Dimensions</b>
<b>Cluster (<math>i = 1 \dots 5</math>)</b>	
Cluster sequence number	1
Normal capacity	1
Maximum capacity if elastic	1
Cluster heterogeneity factor	1
Occupation status (latest 105 steps)*	105 $\rightarrow$ 150
Current total missing deadlines	1
	<b>775 (155 <math>\times</math> 5)</b>
<b>Job</b>	
Category	1
Expected heterogeneity factor	1
Heterogeneity sensitivity	1
Discrete resource request distribution	10 $\times$ 5
Standard execution time	1 $\times$ 5
Execution deadline	1 $\times$ 5
Duration	1
	<b>64</b>
<b>Overall state vector</b>	<b>839 (775 + 64)</b>
<b>Only * row includes temporal information</b>	



# DRL based Approach

- Value definition ideas:
  - Attend to causes of missing deadlines.
  - Attend to job's influence on resource competition.
  - Attend to mutual influences among jobs in cluster.
  - Attend to influences of heterogeneity and elasticity.
  - Attend to both missing deadlines and execution delay ratio.

- Value formula: 
$$v^{(j)} = \frac{\eta_c \cdot m_{ih} \cdot m_{ic}}{-\eta_j} \left[ M_j + \sum_{t=t_s}^{t_e} \beta^{D_t} \left( W_j^{(t)} + W_{cl}^{(t)} \right) \right] - \psi_{ih} \cdot \psi_{ic} \cdot R_j$$

$\eta_c$ : The heterogeneity factor of the cluster.

$\eta_j$ : The expected heterogeneity factor of the job.

$M_j$ : The number of missing deadlines of job j without resource waiting.

$W_j^{(t)}$ : The happening of each missing deadline event of job j at moment t, if not in  $M_j$ .

$W_{cl}^{(t)}$ : The number of missing deadlines of all jobs in the cluster at t if with resource waiting.

$t_s$  and  $t_e$ : The deployment and termination moment of job j.

$\beta$ : The decay factor.

$D_t$ : Number of new jobs deployed to the cluster after  $t_s$ , till moment t.

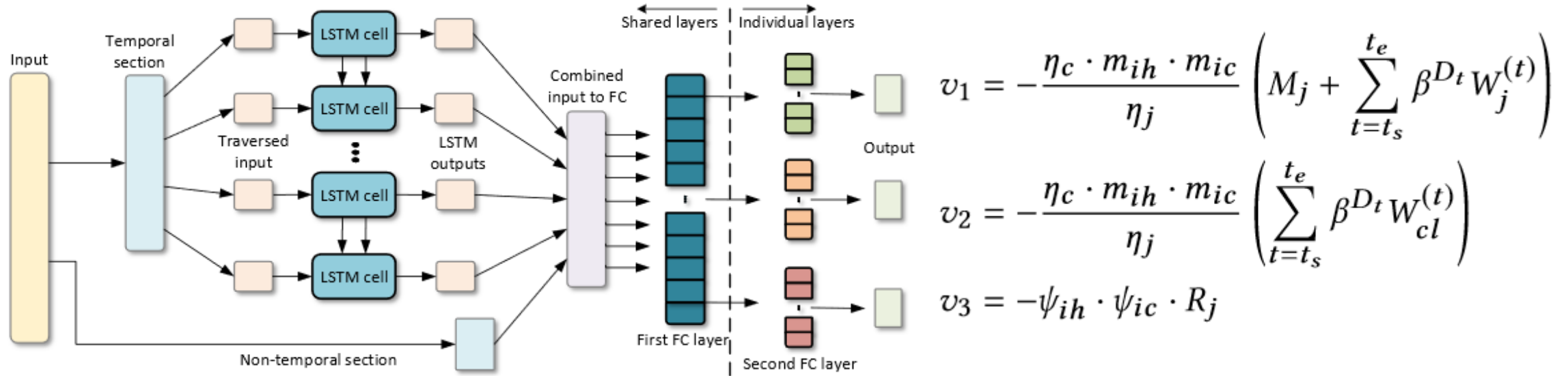
$R_j$ : The overall average execution delay ratio of job j.

$m_{ih}, m_{ic}, \psi_{ih}$  and  $\psi_{ic}$ : penalty terms w.r.t. Improper Heterogeneity and Initial Competition.



# DRL based Approach

- DRL model structure and value definition decomposition

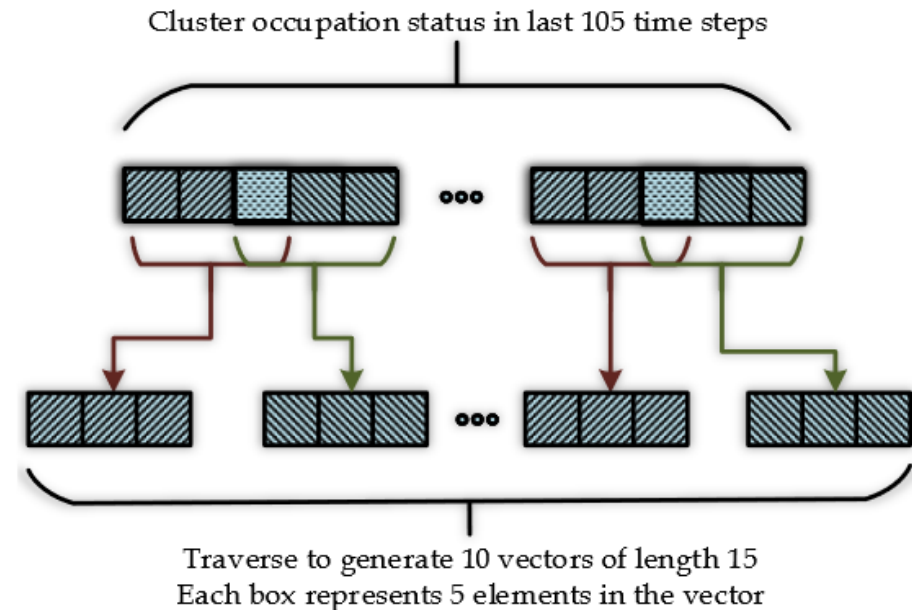




# DRL based Approach

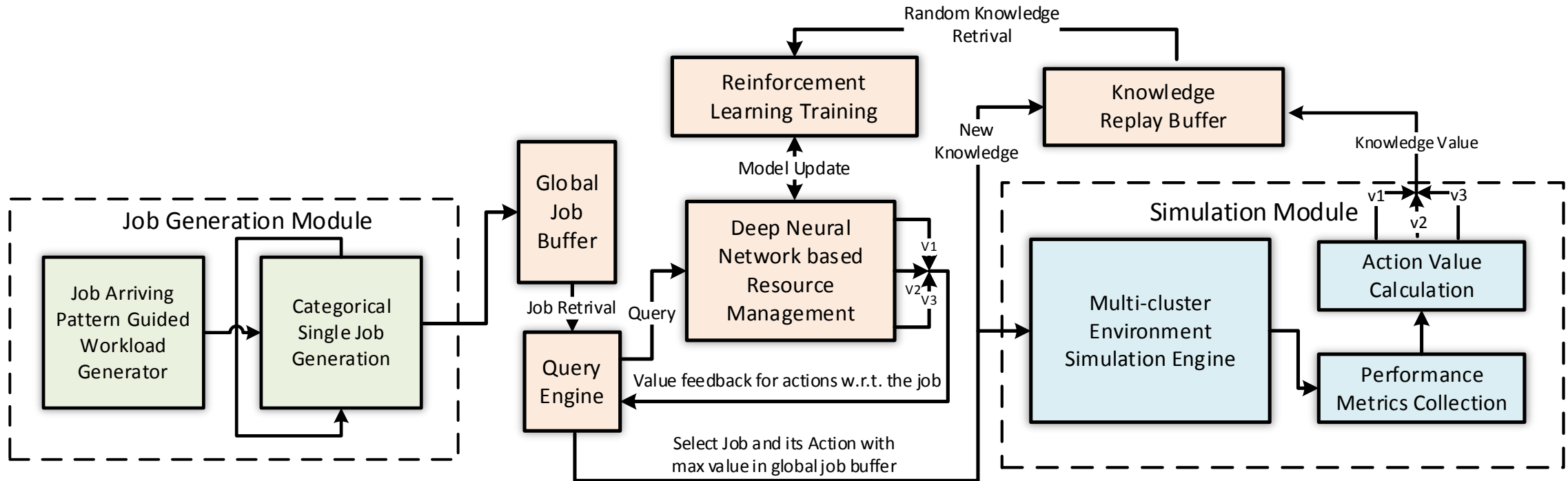
- Training Enhancement Skills
  - Cluster occupation status traverse.
    - Towards better cooperation with LSTM.
  - Training with decayed learning rate.
    - Towards finer model adjustment at later episodes in training.
  - Training with randomized workload.
    - Towards more general knowledge from various workloads.
  - Modified  $\epsilon$ -greedy exploration.
    - Towards utilizing knowledge of rule-based model to partially guide exploration.
  - Solving multi-job selection dilemma
    - Towards coping with jobs in the job buffer.

Cluster occupation status traverse:



# DRL based Approach

- Training architecture



# Experiments

- Introduction
  - Experiment via simulation with a testing environment of 5 clusters. Clusters in this environment are heterogeneous and 2 of the clusters have elasticity as well.
- Elasticity controller
- Local intra-cluster scheduler



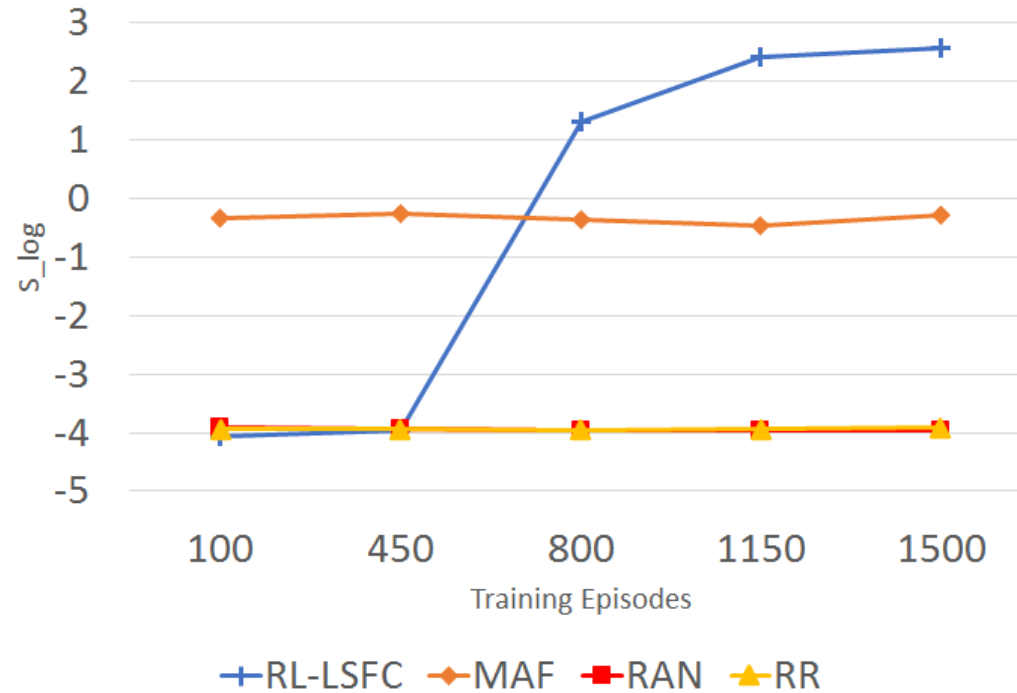
# Experiments

- Comparison:
  - Rule-based baselines:
    - Random (RAN)
    - Round-Robin (RR)
    - Most Available First (MAF)
  - Another RL approach:
    - RL-FC
- Job arriving patterns:
  - Uniform, Bernoulli and Beta
- Performance metrics:
  - TMDL:
    - Total number of occurrences of missing deadlines for all jobs in all clusters during the execution of the workload.
  - AJER:
    - Average job execution time ratio among all clusters
  - $S_{log}$

$$S_{log} = sign(S) * \log_{10}(\max(|S|, 1)) \text{ as } S = -TMDL + 50 * (100 - AJER)$$



# Experiments

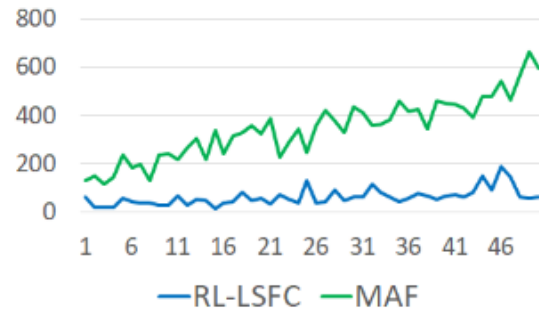


Performance comparison ( $S_{log}$ ) of our deep RL approach RL-LSFC and baseline approaches in different training episodes.

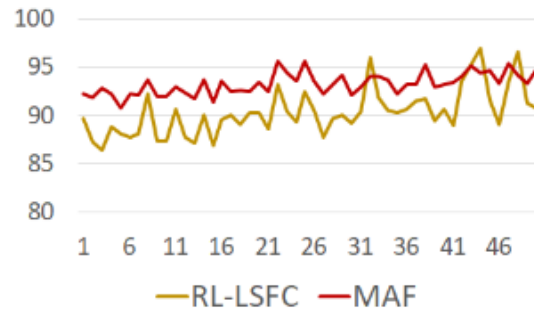


# Experiments

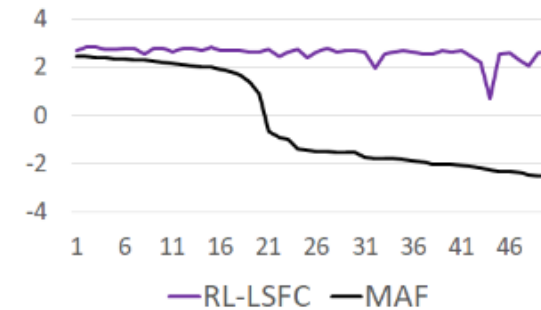
Comparison of RL-LSFC and MAF for 50 testing episodes. (L) lower is better. (H) higher is better. Fully-dominant(F), Semi-dominant(S) or Non-dominant(N) receives score 1 in an episode, if our approach is better than MAF in both, only one or none of the two metrics (TMDL and AJER).



(a) TMDL (L)



(b) AJER (L)



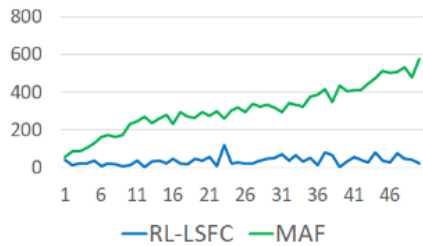
(c)  $S_{log}$  (H)

	TMDL (L)	AJER (L)	$S_{log}$ (H)	F/S/N
RL-LSFC	<b>61.70</b>	<b>90.30</b>	<b>2.57</b>	46/4/0
MAF	343.84	93.22	-0.28	-

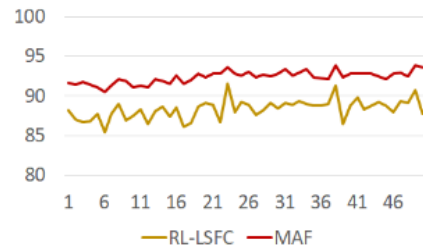


# Experiments

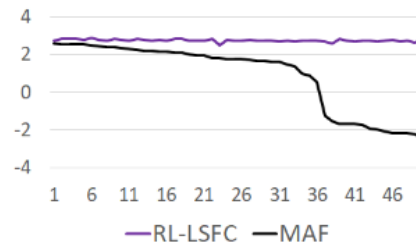
Comparison of RL-LSFC and MAF in variant workloads.  
 (a)-(c) are related to  $b=36$  scenario. (d)-(f) are related to  $b=40$ . Here  $b$  is a parameter in Uniform job pattern.



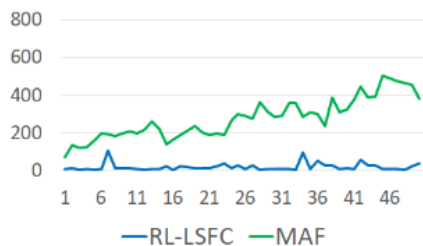
(a) TMDL (L)



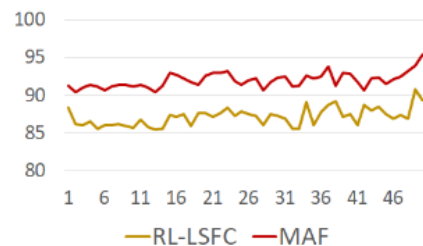
(b) AJER (L)



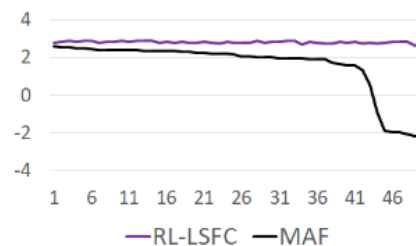
(c)  $S_{log}$  (H)



(d) TMDL (L)



(e) AJER (L)



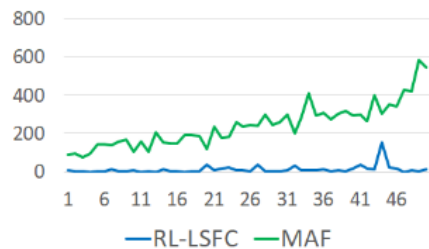
(f)  $S_{log}$  (H)

(a)-(c)	TMDL (L)	AJER (L)	$S_{log}$ (H)	F/S/N
RL-LSFC	<b>37.66</b>	<b>88.32</b>	<b>2.73</b>	50/0/0
MAF	311.44	92.35	0.87	-
(d)-(f)	TMDL (L)	AJER (L)	$S_{log}$ (H)	F/S/N
RL-LSFC	<b>19.76</b>	<b>87.12</b>	<b>2.79</b>	50/0/0
MAF	276.1	91.95	1.55	-

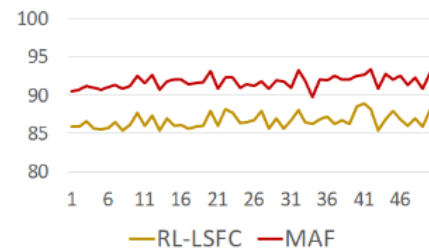


# Experiments

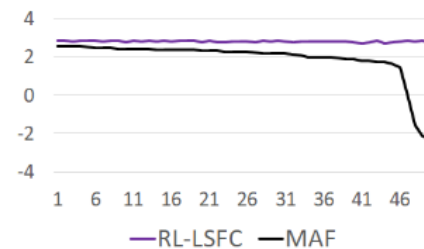
Comparison of RL-LSFC and MAF in other job arriving patterns. (a)-(c): Bernoulli pattern. (d)-(f): Beta pattern.



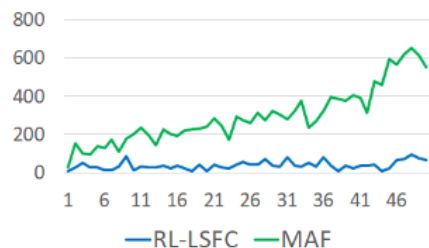
(a) TMDL (L)



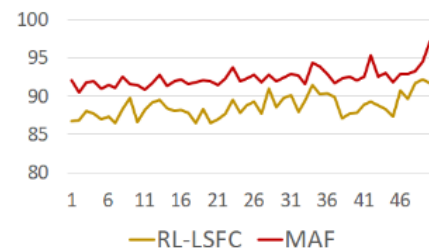
(b) AJER (L)



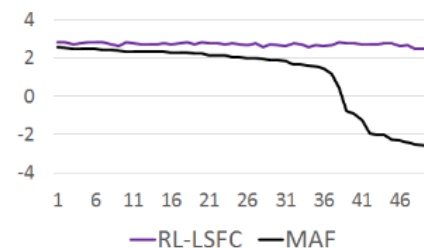
(c)  $S_{log}$  (H)



(d) TMDL (L)



(e) AJER (L)



(f)  $S_{log}$  (H)

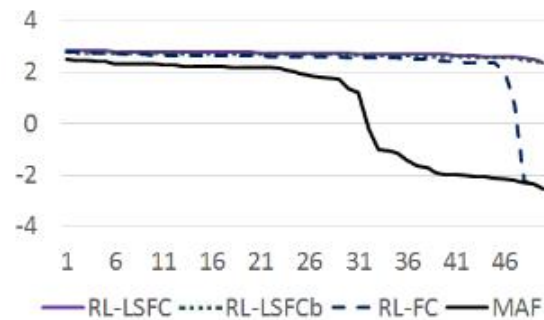
(a)-(c)	TMDL (L)	AJER (L)	$S_{log}$ (H)	F/S/N
RL-LSFC	<b>13.32</b>	<b>86.67</b>	<b>2.81</b>	50/0/0
MAF	243.18	91.75	1.92	-
(d)-(f)	TMDL (L)	AJER (L)	$S_{log}$ (H)	F/S/N
RL-LSFC	<b>39.14</b>	<b>88.68</b>	<b>2.71</b>	50/0/0
MAF	295.66	92.41	1.11	-



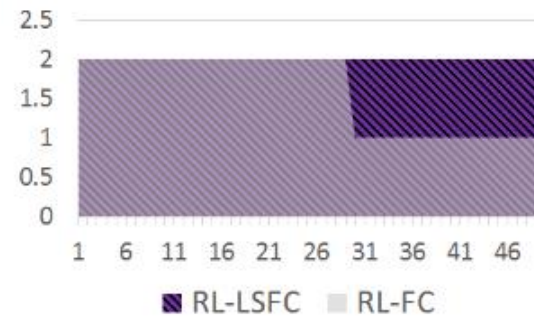


# Experiments

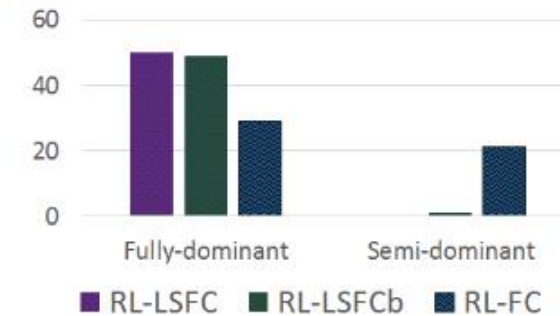
Comparison of three RL models w.r.t. MAF. In (b), we give F:2, S:1 and N:0 for scoring to show a dominant area (larger is better) of RL-LSFC (RL-LSFCb is very similar to RL-LSFC here, so omitted for viewing) and RL-FC.



(a)  $S_{log} (H)$



(b) Dominant area

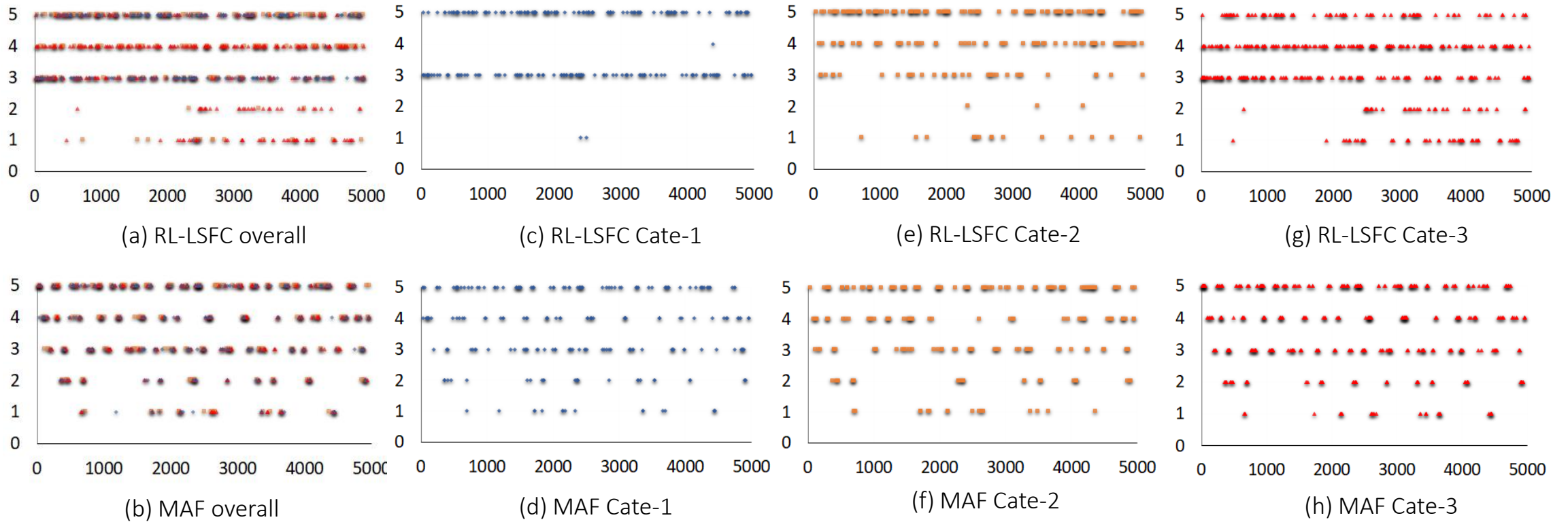


(c) F/S/N distribution

	TMDL (L)	AJER (L)	$S_{log} (H)$	F/S/N
RL-LSFC*	36.84	<b>88.71</b>	<b>2.71</b>	<b>50/0/0</b>
RL-LSFCb*	<b>14.74</b>	90.13	2.67	49/1/0
RL-FC	15.28	92.79	2.24	29/21/0
MAF	305.02	92.67	0.65	-



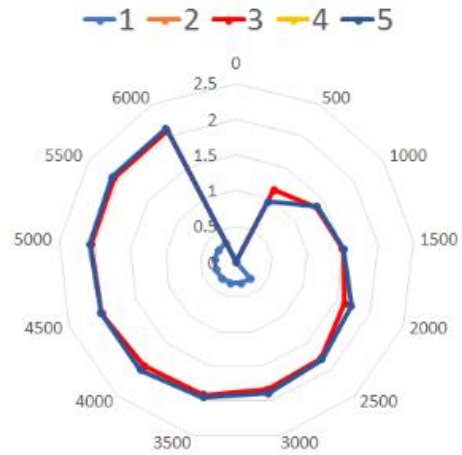
# Experiments



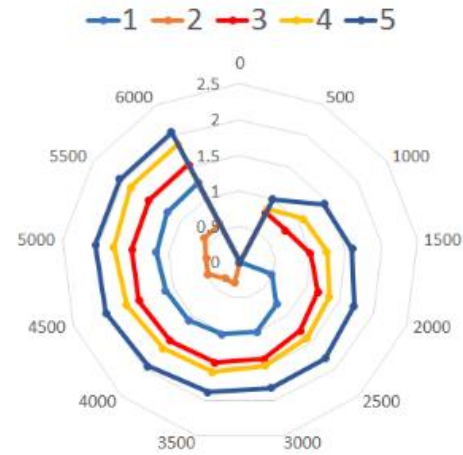
Job-Cluster scheduling patterns for RL-LSFC and MAF in one testing episode. One point for each job and one color for each job category. Vertical axis 1-5 is referring to cluster sequence number. Horizontal axis is time slice.



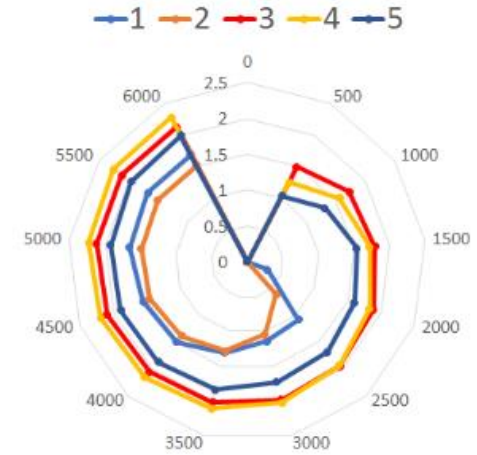
# Experiments



RL-LSFC Cate-1



RL-LSFC Cate-2



RL-LSFC Cate-3

Comparison of Job-Cluster scheduling pattern with respect to different job categories under RL-LSFC control. Value axis is on logarithmic scale of job counts; angle axis is time slice. One color for each cluster.



# Conclusion

- Obtained an elasticity-compatible resource management via DRL for a heterogeneous multi-cluster environment.
- Comparing to the best baseline, it
  - reduces the occurrence of missing execution deadline events for workloads of 1000 jobs by around 5x to 18x,
  - and reduces average execution time ratio by around 2% to 5%.
- Also shows better performance than a previous reinforcement learning based approach with fully-connected layers.

